

WEST Search History

DATE: Monday, August 06, 2007

Hide?	<u>Set</u> <u>Name</u>	<u>Query</u>	<u>Hit</u> <u>Count</u>
	<i>DB=PGPB,USPT,EPAB,JPAB,DWPI,TDBD; PLUR=YES; OP=ADJ</i>		
<input type="checkbox"/>	L46	robot and L45	5
<input type="checkbox"/>	L45	control and "gain phase compensation" and "servo controller"	5
<input type="checkbox"/>	L44	L43 and L28	422
<input type="checkbox"/>	L43	(700/245 700/247 700/249 700/250 700/252 700/253 700/258 700/260 700/264 or 318/568.1 318/568.11 318/568.12 318/568.16 318/568.17 318/568.22 318/.568.25 or 901/1 901/2 901/9 or 180/8.1 180/8.6).cccls.	6926
<input type="checkbox"/>	L42	floor and L41	13
<input type="checkbox"/>	L41	force\$ and L40	13
<input type="checkbox"/>	L40	control\$4 and L39	13
<input type="checkbox"/>	L39	actuator and L38	13
<input type="checkbox"/>	L38	value and L37	14
<input type="checkbox"/>	L37	joint\$ and L36	14
<input type="checkbox"/>	L36	stairs and L35	17
<input type="checkbox"/>	L35	L30 and difference and floor	96
<input type="checkbox"/>	L34	L32 and L30	0
<input type="checkbox"/>	L33	second yoke and (L32 or L31)	1
<input type="checkbox"/>	L32	(5746771 5280783 4329982 4834073 6077203 6203511 4782827 5239987 5399147 6042520 4825852 4803975 4784663 5735905 5755807 4770661 4795471 5928175 6120510 3925824 3863273 3795922 4172296 4123806 4266302 4279042 4285071 4287617 4338926 4417571 4487203 4520512 4520511 4524766 4530114 4532660 4536894 4551863 4567885 4614518 4621629 4762122 4770659 4798610 4815454 4822368 4828565 4834081 4846840 4904265).pn.	105
<input type="checkbox"/>	L31	legged robot	321
<input type="checkbox"/>	L30	reaction force and correction and calculat\$4 and leg\$4 and robot\$6	144
<input type="checkbox"/>	L29	10/476153	4
<input type="checkbox"/>	L28	robot\$6 and (walk\$3 or biped or humanoid or two legged) and (inlina\$6 or betn or tilt or deviat\$5 or obliqu\$5 or indirect\$4 or change direction or slope or slant)	4929
<input type="checkbox"/>	L27	('6711469' '6697709' '6567724' '6505098' '6493606' '6480761' '6330494' '6289265' '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	16
<input type="checkbox"/>	L26	marc.xa. and legged and inclination	26
<input type="checkbox"/>	L25	marc.xa. and legged and inclinaiton	0
<input type="checkbox"/>	L24	('5404086')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L23	(edditng or updating) and (motion or traject\$4 or movement) and zmp and robot\$6	16

<input type="checkbox"/>	L22	(edditng or updating) same (motion or traject\$4 or movement) and zmp and robot\$6	8
<input type="checkbox"/>	L21	(edditng or updating) same (motion or traject\$4 or movement) and L20	7
<input type="checkbox"/>	L20	robot and zmp and yaw	128
<input type="checkbox"/>	L19	marc.xa. and zmp	33
<input type="checkbox"/>	L18	10/181500	3
<input type="checkbox"/>	L17	('6697709' '6289265' '6243623')!.ABPN1,NRPN,PN,TBAN,WKU.	6
<input type="checkbox"/>	L16	marc.xa. and robot and zmp	33
<input type="checkbox"/>	L15	(motions or movement or displacement) and L14	91
<input type="checkbox"/>	L14	computer and L13	102
<input type="checkbox"/>	L13	record\$3 and L12	102
<input type="checkbox"/>	L12	(request or command) and L11	122
<input type="checkbox"/>	L11	L7 and L10	127
<input type="checkbox"/>	L10	execut\$5 and L9	242486
<input type="checkbox"/>	L9	run or L7	1209830
<input type="checkbox"/>	L8	(6458772 or 6284156 or 6348461 or 6262044 or 6410586 or 6342245 or 6277877 or 6399557 or 3857856 or 5835892 or 6376445 or 6440911 or 6163111 or 5610305 or 5230889 or 4391489 or 4483594 or 6410749 or 4876009 or 6358945 or 6281227 or 6391397 or 6432994 or 4920120 or 5874378 or 6374641 or 5384779 or 5523998 or 5537098 or 4260406 or 4293439 or 4386503 or 5179438 or 5208607 or 6275216 or 5534261 or 5640119 or 5831440 or 6049212 or 6271251 or 4949326 or 5015815 or 5194938 or 4870247 or 6258470 or 6316465 or 6388989 or 4505827 or 5210848 or 5230070).pn.	99
<input type="checkbox"/>	L7	(similar or "same") function and L6	149
<input type="checkbox"/>	L6	robot and control software and (chang\$3 or replac\$5)	1716
<input type="checkbox"/>	L5	('20050125099')!.ABPN1,NRPN,PN,TBAN,WKU.	2
<input type="checkbox"/>	L4	(10/126774 10/970977 10/935607 10/919172 10/775845 10/732446 10/726597 10/683496 10/637890)	17
<input type="checkbox"/>	L3	(motion or displacement or trajector\$3) and L2	97
<input type="checkbox"/>	L2	(humanoid or two legged robot and human like robot) and zmp and comput\$5	100
<input type="checkbox"/>	L1	10/726597	1

END OF SEARCH HISTORY